

# Engineering Optimization: Lecture 1

Pravesh Biyani

IIIT Delhi

August 4, 2015

# Course Organization

- ▶ 13 Weeks, Tue and Fri: 9:30 to 11:00 A.M
- ▶ Course Website: Coming Soon !
- ▶ Office hours: Wed: 12:00 to 1:00 p.m
- ▶ References :
  - ▶ **Convex Optimization** by Boyd and Vandenberghe  
<http://www.stanford.edu/boyd/cvxbook/>
  - ▶ **Introduction to Convex Programming** by Y. Nesterov  
<http://www.core.ucl.ac.be/nesterov/Courses/INMA2460/Intro-nl.pdf>
  - ▶ **Non-linear Programming** by Dimitri Bertsekas

## Course Organization..

- ▶ 4 assignments/quizzes (including one possible programming assignment) – 15%
- ▶ One minor exam (open notes, your notes, no photocopies) – 25%
- ▶ 1 major exam (open notes, your notes, no photocopies) – 40%
- ▶ One course project – 20% (Only for those who satisfy Minimum requirements)
- ▶ Optimization of **Grades** is optimization of effort.
- ▶ Any other suggestion on evaluation?

# Course Topics

- ▶ Mathematical review: Linear Algebra, Vector Calculus.
- ▶ How to frame Optimization problems?
- ▶ Convex sets and functions
- ▶ Introductory non-linear programming: Gradient descent algorithms etc.
- ▶ Convex Optimization problems: LP, QP etc.
- ▶ Duality and Lagrangian Relaxation techniques
- ▶ Algorithms for Optimizations
- ▶ Applications to Machine learning, Communications, Signal Processing etc.

# What is Optimization

$$\begin{array}{ll} \min & f(x) \\ \text{subject to} & x \in \chi \end{array} \quad (1)$$

where

- ▶  $x$  is a decision variable
- ▶  $f(x)$  is the objective function (convex, linear, non-linear..)
- ▶  $\chi$  is the feasible region (convex, non-empty)

Key questions:

- ▶ Is the problem feasible?
- ▶ How to determine if a candidate  $x$  is an optimal solution.
- ▶ How to find the optimal solution.

# Applications

- ▶ Signal processing and (wireless and wireline) Communications
- ▶ VLSI
- ▶ Machine Learning and Vision
- ▶ Robotics
- ▶ Finance and Analytics
- ▶ Computational Biology
- ▶ Operations Research

## Who should not take this course

- ▶ If you have a dislike for Maths – Linear Algebra, Calculus
- ▶ If you plan to attend less than 80% classes.
- ▶ If any one of the above is true.

# How do I use optimization?

Questions:

- ▶ What are the possible methods to find a good solution?
- ▶ Is the problem convex?
- ▶ Does my algorithm converge to an optimal solution?
- ▶ How do I initialize my algorithm?
- ▶ What is the run-time complexity of the algorithm?

Answer: This course!



# Review of Basics: Vector Calculus

- ▶ Limit
- ▶ Continuity
- ▶ Gradient

$$\nabla(f(x)) = \left[ \frac{\partial f(x)}{\partial x_1} \quad \frac{\partial f(x)}{\partial x_2} \quad \cdots \quad \frac{\partial f(x)}{\partial x_N} \right]^T$$

- ▶ Taylor Series Expansion of functions
  - ▶ Expansion used to approximate complicated functions.

## Norms

$f : \mathbf{R}^n \rightarrow \mathbf{R}$  is a norm if for all  $x, y \in \mathbf{R}^n$ ,  $t \in \mathbf{R}$  s

1.  $f(x) \geq 0$
2.  $f(tx) = |t|f(x)$
3.  $f(x + y) \leq f(x) + f(y)$

$f(x)$  usually denoted as  $\| \cdot \|_{\text{mark}}$

Example:  $\| \cdot \|_2$ , called  $l_2$  norm or the euclidean norm.

In general  $l_p$  norms are  $\| \cdot \|_p$ ,  $p \geq 1$ , where,

$$\|x\|_p = \left( \sum_i |x_i|^p \right)^{\frac{1}{p}}$$